

# Support Vector Machines

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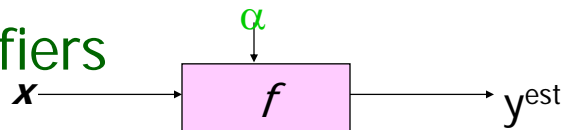
[awm@cs.cmu.edu](mailto:awm@cs.cmu.edu)

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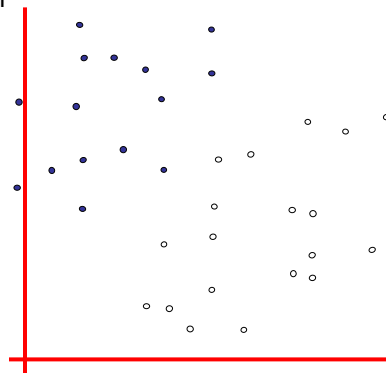
Nov 23rd, 2001

## Linear Classifiers



$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

- denotes +1
- denotes -1

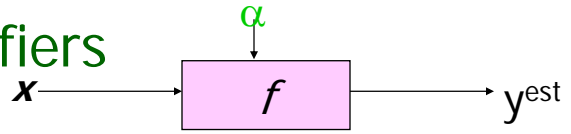


How would you classify this data?

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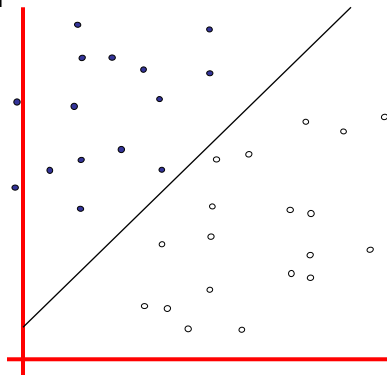
Support Vector Machines: Slide 2

# Linear Classifiers



$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

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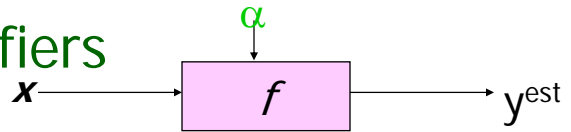


How would you classify this data?

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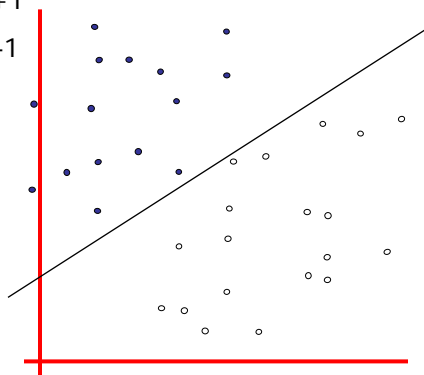
Support Vector Machines: Slide 3

# Linear Classifiers



$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

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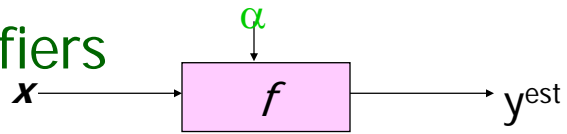


How would you classify this data?

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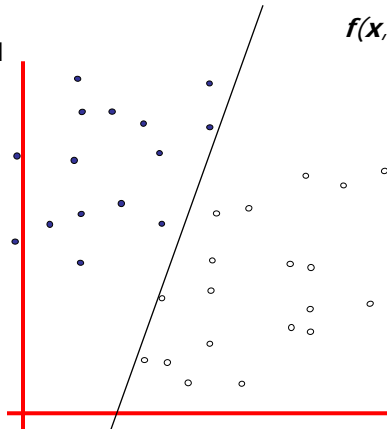
Support Vector Machines: Slide 4

# Linear Classifiers



$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \mathbf{x} - b)$$

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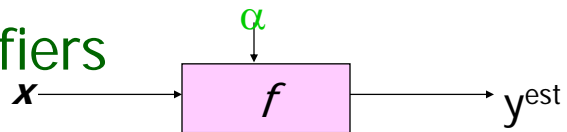


How would you classify this data?

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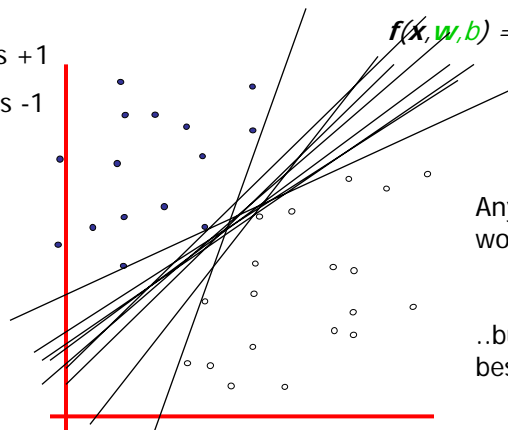
Support Vector Machines: Slide 5

# Linear Classifiers



$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \mathbf{x} - b)$$

- denotes +1
- denotes -1



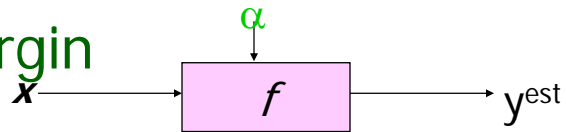
Any of these would be fine..

..but which is best?

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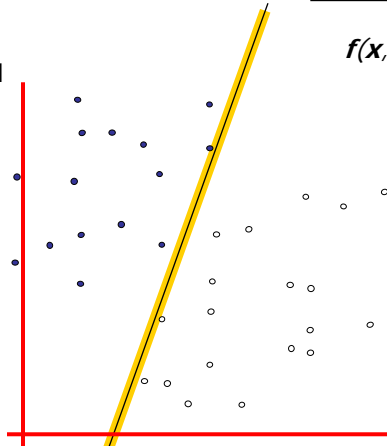
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# Classifier Margin



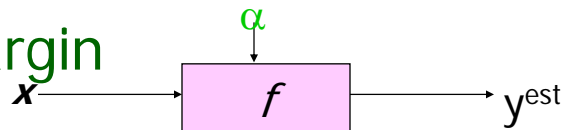
$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

- denotes +1
- denotes -1



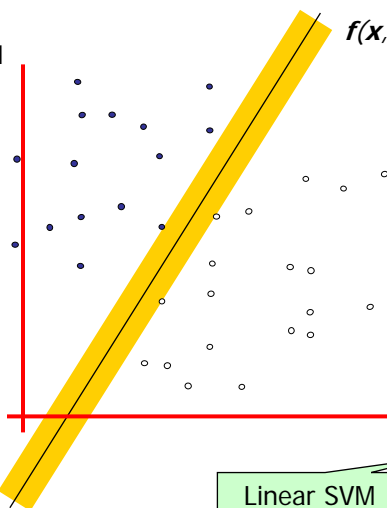
Define the **margin** of a linear classifier as the width that the boundary could be increased by before hitting a datapoint.

# Maximum Margin



$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

- denotes +1
- denotes -1

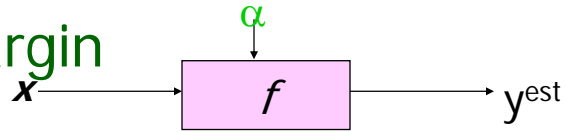


The **maximum margin linear classifier** is the linear classifier with the, um, maximum margin.

This is the simplest kind of SVM (Called an LSVM)

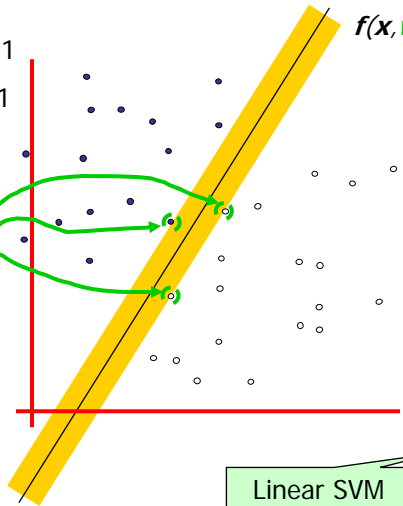
Linear SVM

# Maximum Margin



- denotes +1
- denotes -1

Support Vectors are those datapoints that the margin pushes up against



$$f(x, w, b) = \text{sign}(w \cdot x - b)$$

The **maximum margin linear classifier** is the linear classifier with the, um, maximum margin.

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Linear SVM

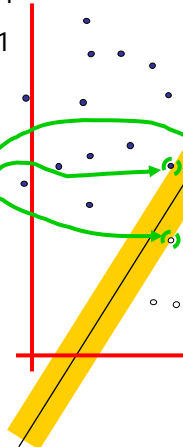
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Support Vector Machines: Slide 9

# Why Maximum Margin?

- denotes +1
- denotes -1

Support Vectors are those datapoints that the margin pushes up against

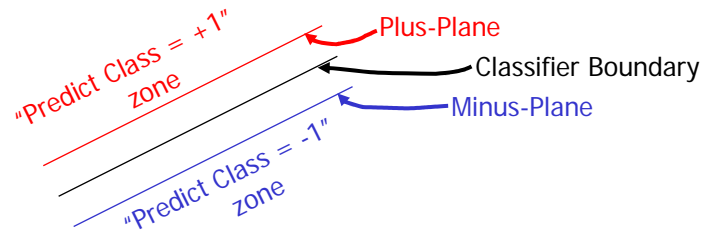


1. Intuitively this feels safest.
2. If we've made a small error in the location of the boundary (it's been jolted in its perpendicular direction) this gives us least chance of causing a misclassification.
3. LOOCV is easy since the model is immune to removal of any non-support-vector datapoints.
4. There's some theory (using VC dimension) that is related to (but not the same as) the proposition that this is a good thing.
5. Empirically it works very very well.

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Support Vector Machines: Slide 10

## Specifying a line and margin

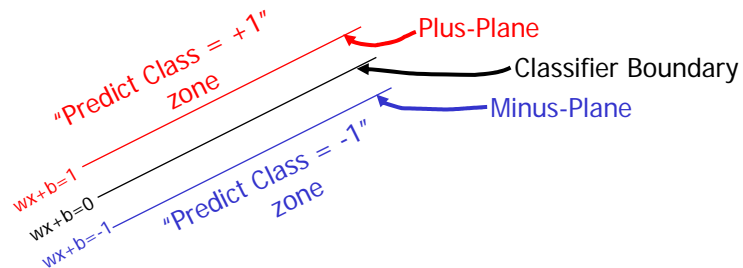


- How do we represent this mathematically?
- ...in  $m$  input dimensions?

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Support Vector Machines: Slide 11

## Specifying a line and margin



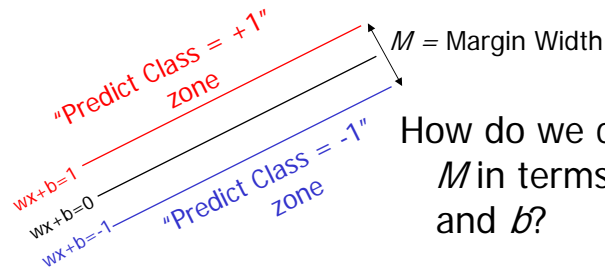
- Plus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = +1 \}$
- Minus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = -1 \}$

Classify as..  $+1$  if  $\mathbf{w} \cdot \mathbf{x} + b \geq 1$   
 $-1$  if  $\mathbf{w} \cdot \mathbf{x} + b \leq -1$   
 Universe explodes if  $-1 < \mathbf{w} \cdot \mathbf{x} + b < 1$

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Support Vector Machines: Slide 12

## Computing the margin width

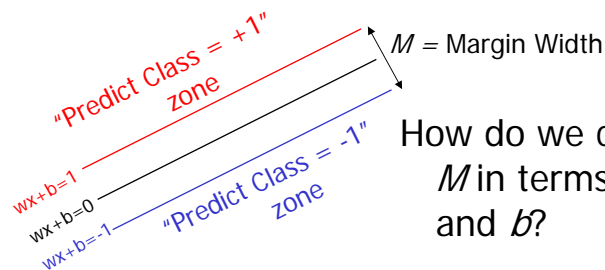


How do we compute  $M$  in terms of  $w$  and  $b$ ?

- Plus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = +1 \}$
- Minus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = -1 \}$

**Claim:** The vector  $\mathbf{w}$  is perpendicular to the Plus Plane. **Why?**

## Computing the margin width



How do we compute  $M$  in terms of  $w$  and  $b$ ?

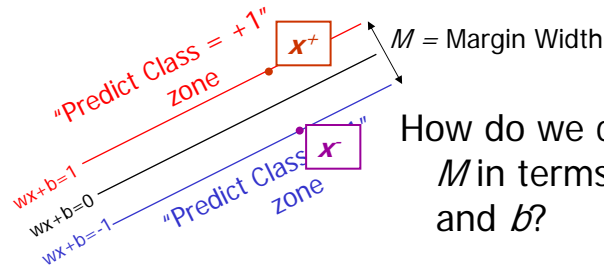
- Plus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = +1 \}$
- Minus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = -1 \}$

**Claim:** The vector  $\mathbf{w}$  is perpendicular to the Plus Plane. **Why?**

Let  $\mathbf{u}$  and  $\mathbf{v}$  be two vectors on the Plus Plane. What is  $\mathbf{w} \cdot (\mathbf{u} - \mathbf{v})$ ?

And so of course the vector  $\mathbf{w}$  is also perpendicular to the Minus Plane

## Computing the margin width



How do we compute  $M$  in terms of  $w$  and  $b$ ?

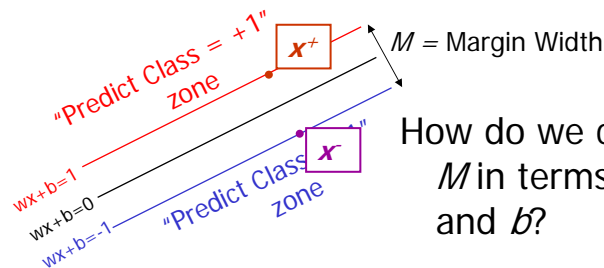
- Plus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = +1 \}$
- Minus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = -1 \}$
- The vector  $\mathbf{w}$  is perpendicular to the Plus Plane
- Let  $\mathbf{x}^*$  be any point on the minus plane
- Let  $\mathbf{x}^+$  be the closest plus-plane-point to  $\mathbf{x}^*$ .

Any location in  $\mathbb{R}^m$ : not necessarily a datapoint

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Support Vector Machines: Slide 15

## Computing the margin width



How do we compute  $M$  in terms of  $w$  and  $b$ ?

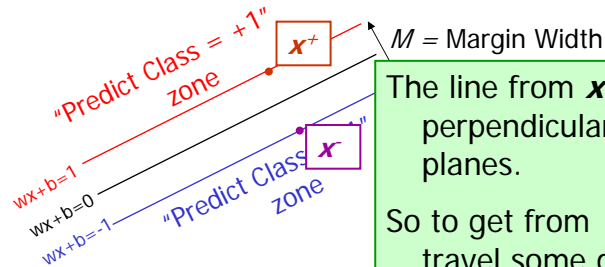
- Plus-plane =  $\{ \mathbf{x} : \mathbf{w} \cdot \mathbf{x} + b = +1 \}$
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- The vector  $\mathbf{w}$  is perpendicular to the Plus Plane
- Let  $\mathbf{x}^*$  be any point on the minus plane
- Let  $\mathbf{x}^+$  be the closest plus-plane-point to  $\mathbf{x}^*$ .
- **Claim:**  $\mathbf{x}^+ = \mathbf{x}^* + \lambda \mathbf{w}$  for some value of  $\lambda$ . **Why?**

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Support Vector Machines: Slide 16



## Computing the margin width



The line from  $x^-$  to  $x^+$  is perpendicular to the planes.

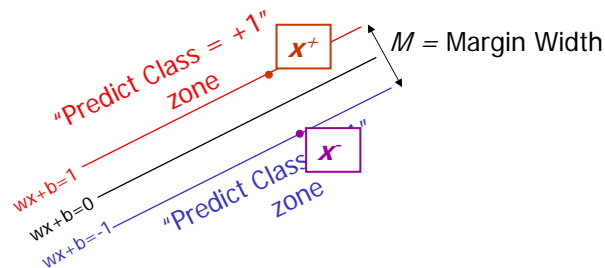
So to get from  $x^-$  to  $x^+$  travel some distance in direction  $w$ .

- Plus-plane =  $\{x : w \cdot x + b = 1\}$
- Minus-plane =  $\{x : w \cdot x + b = -1\}$
- The vector  $w$  is perpendicular to the Plus Plane
- Let  $x^-$  be any point on the minus plane
- Let  $x^+$  be the closest plus-plane-point to  $x^-$ .
- **Claim:**  $x^+ = x^- + \lambda w$  for some value of  $\lambda$ . **Why?**

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Support Vector Machines: Slide 17

## Computing the margin width



What we know:

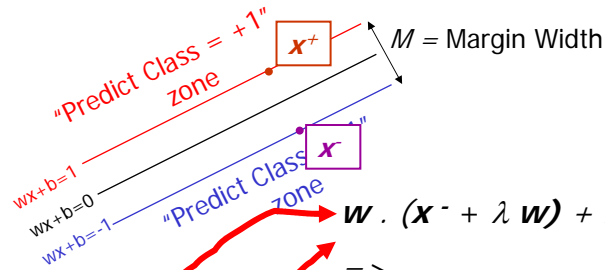
- $w \cdot x^+ + b = +1$
- $w \cdot x^- + b = -1$
- $x^+ = x^- + \lambda w$
- $|x^+ - x^-| = M$

It's now easy to get  $M$   
in terms of  $w$  and  $b$

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Support Vector Machines: Slide 18

## Computing the margin width



What we know:

- $w \cdot x^+ + b = +1$
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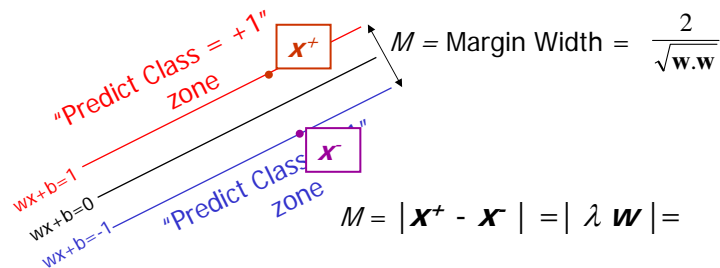
It's now easy to get  $M$  in terms of  $w$  and  $b$

$$\begin{aligned} w \cdot (x^- + \lambda w) + b &= 1 \\ \Rightarrow w \cdot x^- + b + \lambda w \cdot w &= 1 \\ \Rightarrow -1 + \lambda w \cdot w &= 1 \\ \Rightarrow \lambda &= \frac{2}{w \cdot w} \end{aligned}$$

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Support Vector Machines: Slide 19

## Computing the margin width



What we know:

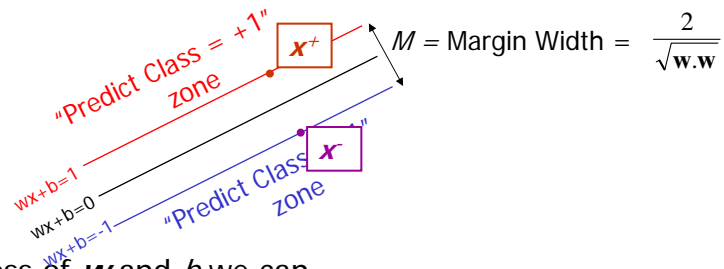
- $w \cdot x^+ + b = +1$
- $w \cdot x^- + b = -1$
- $x^+ = x^- + \lambda w$
- $|x^+ - x^-| = M$
- $\lambda = \frac{2}{w \cdot w}$

$$\begin{aligned} M &= |x^+ - x^-| = |\lambda w| \\ &= \lambda |w| = \lambda \sqrt{w \cdot w} \\ &= \frac{2\sqrt{w \cdot w}}{w \cdot w} = \frac{2}{\sqrt{w \cdot w}} \end{aligned}$$

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Support Vector Machines: Slide 20

## Learning the Maximum Margin Classifier



Given a guess of  $\mathbf{w}$  and  $b$  we can

- Compute whether all data points in the correct half-planes
- Compute the width of the margin

So now we just need to write a program to search the space of  $\mathbf{w}$ 's and  $b$ 's to find the widest margin that matches all the datapoints. *How?*

Gradient descent? Simulated Annealing? Matrix Inversion?  
EM? Newton's Method?

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Support Vector Machines: Slide 21

## Learning via Quadratic Programming

- QP is a well-studied class of optimization algorithms to maximize a quadratic function of some real-valued variables subject to linear constraints.

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Support Vector Machines: Slide 22

# Quadratic Programming

Find  $\arg \max_{\mathbf{u}} c + \mathbf{d}^T \mathbf{u} + \frac{\mathbf{u}^T \mathbf{R} \mathbf{u}}{2}$  ← Quadratic criterion

Subject to

$$\begin{aligned} a_{11}u_1 + a_{12}u_2 + \dots + a_{1m}u_m &\leq b_1 \\ a_{21}u_1 + a_{22}u_2 + \dots + a_{2m}u_m &\leq b_2 \\ &\vdots \\ a_{n1}u_1 + a_{n2}u_2 + \dots + a_{nm}u_m &\leq b_n \end{aligned}$$

} *n* additional linear inequality constraints

And subject to

$$\begin{aligned} a_{(n+1)1}u_1 + a_{(n+1)2}u_2 + \dots + a_{(n+1)m}u_m &= b_{(n+1)} \\ a_{(n+2)1}u_1 + a_{(n+2)2}u_2 + \dots + a_{(n+2)m}u_m &= b_{(n+2)} \\ &\vdots \\ a_{(n+e)1}u_1 + a_{(n+e)2}u_2 + \dots + a_{(n+e)m}u_m &= b_{(n+e)} \end{aligned}$$

} *e* additional linear equality constraints

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Support Vector Machines: Slide 23

# Quadratic Programming

Find  $\arg \max_{\mathbf{u}} c + \mathbf{d}^T \mathbf{u} + \frac{\mathbf{u}^T \mathbf{R} \mathbf{u}}{2}$  ← Quadratic criterion

Subject to

$$\begin{aligned} a_{11}u_1 + a_{12}u_2 + \dots + a_{1m}u_m &\leq b_1 \\ a_{21}u_1 + a_{22}u_2 + \dots + a_{2m}u_m &\leq b_2 \\ &\vdots \\ a_{n1}u_1 + a_{n2}u_2 + \dots + a_{nm}u_m &\leq b_n \end{aligned}$$

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And subject to

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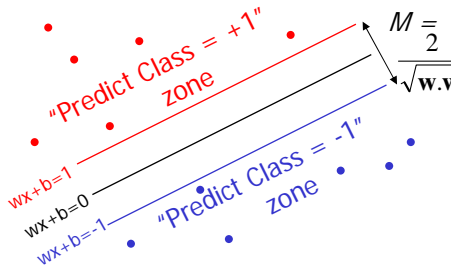
There exist algorithms for finding such constrained quadratic optima much more efficiently and reliably than gradient ascent.

(But they are very fiddly...you probably don't want to write one yourself)

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Support Vector Machines: Slide 24

## Learning the Maximum Margin Classifier



Given guess of  $\mathbf{w}$ ,  $b$  we can

- Compute whether all data points are in the correct half-planes
- Compute the margin width

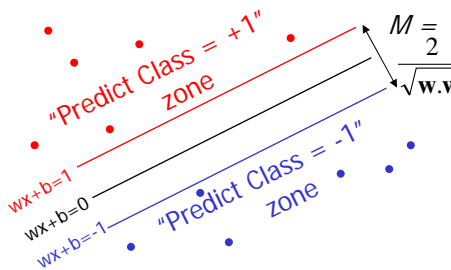
Assume  $R$  datapoints, each  $(\mathbf{x}_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

How many constraints will we have?

What should they be?

## Learning the Maximum Margin Classifier



Given guess of  $\mathbf{w}$ ,  $b$  we can

- Compute whether all data points are in the correct half-planes
- Compute the margin width

Assume  $R$  datapoints, each  $(\mathbf{x}_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

Minimize  $\mathbf{w} \cdot \mathbf{w}$

How many constraints will we have?  $R$

What should they be?

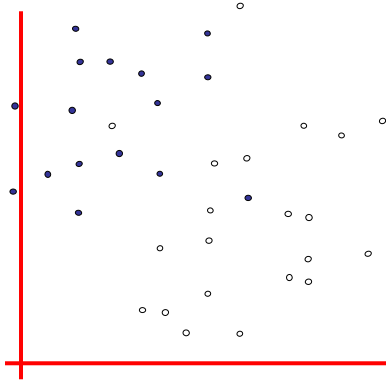
$$\mathbf{w} \cdot \mathbf{x}_k + b \geq 1 \text{ if } y_k = 1$$

$$\mathbf{w} \cdot \mathbf{x}_k + b \leq -1 \text{ if } y_k = -1$$

Uh-oh!

This is going to be a problem!  
What should we do?

- denotes +1
- denotes -1



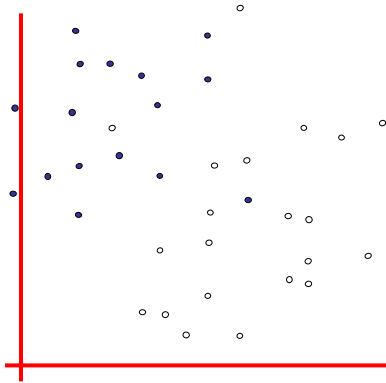
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Support Vector Machines: Slide 27

Uh-oh!

This is going to be a problem!  
What should we do?

- denotes +1
- denotes -1



Idea 1:

Find minimum  $\|w\|$ , while minimizing number of training set errors.

Problem: Two things to minimize makes for an ill-defined optimization

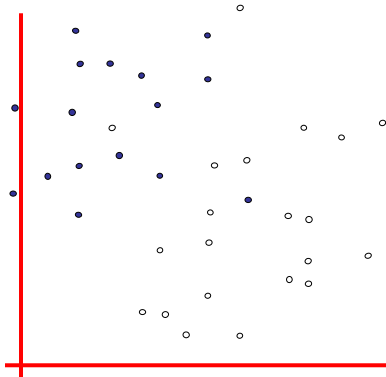
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Support Vector Machines: Slide 28

Uh-oh!

This is going to be a problem!  
What should we do?

- denotes +1
- denotes -1



Idea 1.1:

Minimize

$$w \cdot w + C (\#train\ errors)$$

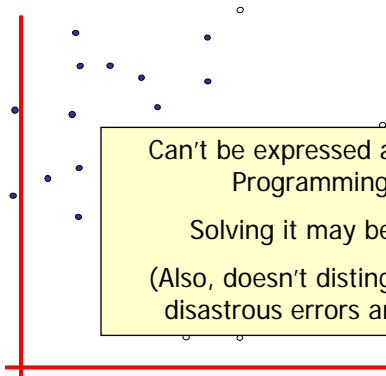
Tradeoff parameter

There's a serious practical problem that's about to make us reject this approach. Can you guess what it is?

Uh-oh!

This is going to be a problem!  
What should we do?

- denotes +1
- denotes -1



Idea 1.1:

Minimize

$$w \cdot w + C (\#train\ errors)$$

Tradeoff parameter

Can't be expressed as a Quadratic Programming problem.  
Solving it may be too slow.  
(Also, doesn't distinguish between disastrous errors and near misses)

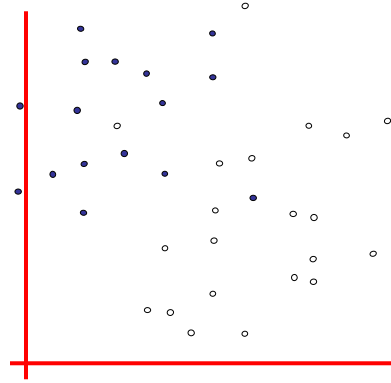
So... any other ideas?

us reject this  
you guess wh

Uh-oh!

This is going to be a problem!  
What should we do?

- denotes +1
- denotes -1



Idea 2.0:

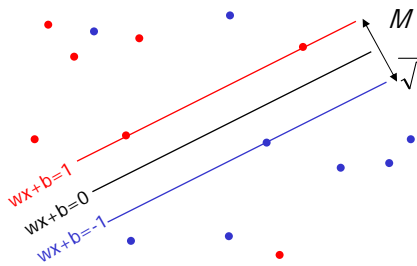
Minimize

$w \cdot w + C$  (distance of error points to their correct place)

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Support Vector Machines: Slide 31

## Learning Maximum Margin with Noise



Given guess of  $w$ ,  $b$  we can

- Compute sum of distances of points to their correct zones

- Compute the margin width

Assume  $R$  datapoints, each  $(x_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

How many constraints will we have?

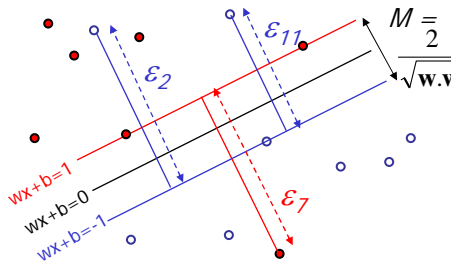
What should they be?

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Support Vector Machines: Slide 32



## Learning Maximum Margin with Noise



- Given guess of  $\mathbf{w}$ ,  $b$  we can
- Compute sum of distances of points to their correct zones
  - Compute the margin width
- Assume  $R$  datapoints, each  $(\mathbf{x}_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

Minimize 
$$\frac{1}{2} \mathbf{w} \cdot \mathbf{w} + C \sum_{k=1}^R \epsilon_k$$

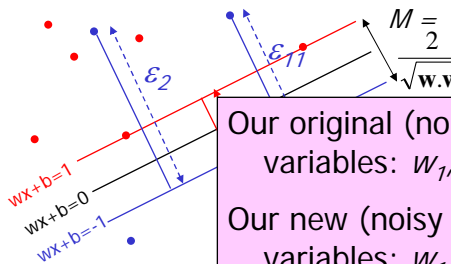
How many constraints will we have?  $R$

What should they be?

$$\mathbf{w} \cdot \mathbf{x}_k + b \geq 1 - \epsilon_k \text{ if } y_k = 1$$

$$\mathbf{w} \cdot \mathbf{x}_k + b \leq -1 + \epsilon_k \text{ if } y_k = -1$$

## Learning Maximum Margin with Noise



$m = \#$  input dimensions

- Given guess of  $\mathbf{w}$ ,  $b$  we can
- Compute sum of distances

Our original (noiseless data) QP had  $m+1$  variables:  $w_1, w_2, \dots, w_m$  and  $b$ .

Our new (noisy data) QP has  $m+1+R$  variables:  $w_1, w_2, \dots, w_m, b, \epsilon_k, \epsilon_1, \dots, \epsilon_R$

What should our quadratic optimization criterion be?

Minimize 
$$\frac{1}{2} \mathbf{w} \cdot \mathbf{w} + C \sum_{k=1}^R \epsilon_k$$

How many constraints will we have?  $R$

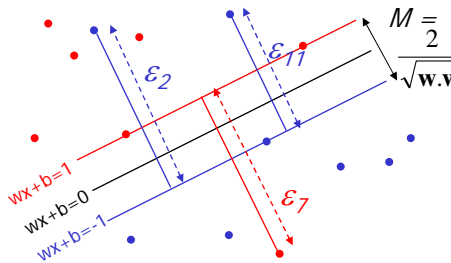
$R = \#$  records

What should they be?

$$\mathbf{w} \cdot \mathbf{x}_k + b \geq 1 - \epsilon_k \text{ if } y_k = 1$$

$$\mathbf{w} \cdot \mathbf{x}_k + b \leq -1 + \epsilon_k \text{ if } y_k = -1$$

## Learning Maximum Margin with Noise



Given guess of  $\mathbf{w}$ ,  $b$  we can

- Compute sum of distances of points to their correct zones

- Compute the margin width

Assume  $R$  datapoints, each  $(\mathbf{x}_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

Minimize 
$$\frac{1}{2} \mathbf{w} \cdot \mathbf{w} + C \sum_{k=1}^R \varepsilon_k$$

How many constraints will we have?  $R$

What should they be?

$\mathbf{w} \cdot \mathbf{x}_k + b \geq 1 - \varepsilon_k$  if  $y_k = 1$

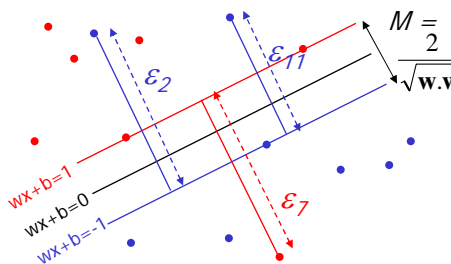
$\mathbf{w} \cdot \mathbf{x}_k + b \leq -1 + \varepsilon_k$  if  $y_k = -1$

There's a bug in this QP. Can you spot it?

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Support Vector Machines: Slide 35

## Learning Maximum Margin with Noise



Given guess of  $\mathbf{w}$ ,  $b$  we can

- Compute sum of distances of points to their correct zones

- Compute the margin width

Assume  $R$  datapoints, each  $(\mathbf{x}_k, y_k)$  where  $y_k = +/- 1$

What should our quadratic optimization criterion be?

Minimize 
$$\frac{1}{2} \mathbf{w} \cdot \mathbf{w} + C \sum_{k=1}^R \varepsilon_k$$

How many constraints will we have?  $2R$

What should they be?

$\mathbf{w} \cdot \mathbf{x}_k + b \geq 1 - \varepsilon_k$  if  $y_k = 1$

$\mathbf{w} \cdot \mathbf{x}_k + b \leq -1 + \varepsilon_k$  if  $y_k = -1$

$\varepsilon_k \geq 0$  for all  $k$

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Support Vector Machines: Slide 36

## An Equivalent QP

Warning: up until Rong Zhang spotted my error in Oct 2003, this equation had been wrong in earlier versions of the notes. This version is correct.

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l (\mathbf{x}_k \cdot \mathbf{x}_l)$$

$$\text{Subject to these constraints: } 0 \leq \alpha_k \leq C \quad \forall k \quad \sum_{k=1}^R \alpha_k y_k = 0$$

Then define:

$$\mathbf{w} = \sum_{k=1}^R \alpha_k y_k \mathbf{x}_k$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \mathbf{x} - b)$$

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Support Vector Machines: Slide 37

## An Equivalent QP

Warning: up until Rong Zhang spotted my error in Oct 2003, this equation had been wrong in earlier versions of the notes. This version is correct.

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l (\mathbf{x}_k \cdot \mathbf{x}_l)$$

$$\text{Subject to these constraints: } 0 \leq \alpha_k \leq C \quad \forall k \quad \sum_{k=1}^R \alpha_k y_k = 0$$

Then define:

$$\mathbf{w} = \sum_{k=1}^R \alpha_k y_k \mathbf{x}_k$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

Datapoints with  $\alpha_k > 0$  will be the support vectors

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \mathbf{x} - b)$$

..so this sum only needs to be over the support vectors.

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Support Vector Machines: Slide 38

## An Equivalent QP

Maximize  $\sum_{k=1}^R \alpha_k$  subject to  $\sum_{k=1}^R \alpha_k y_k y_l (\mathbf{x}_k \cdot \mathbf{x}_l) \leq 0$

Subj  
const

Why did I tell you about this equivalent QP?

- It's a formulation that QP packages can optimize more quickly
- Because of further jaw-dropping developments you're about to learn.

Then

$\mathbf{w} = \sum_{k=1}^R \alpha_k \mathbf{x}_k$

$b = y_K (1 - \alpha_K)$

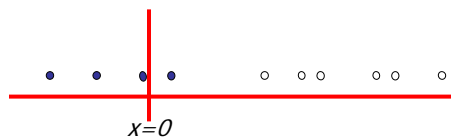
where  $K = \arg \max_k \alpha_k$

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Support Vector Machines: Slide 39

## Suppose we're in 1-dimension

What would SVMs do with this data?

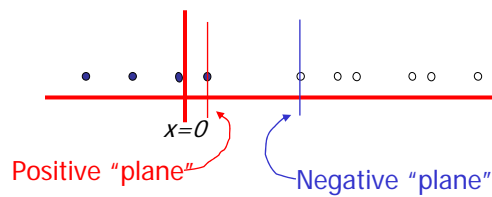


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## Suppose we're in 1-dimension

Not a big surprise



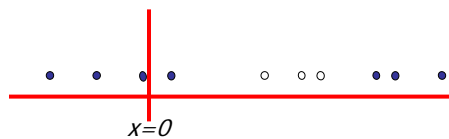
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Support Vector Machines: Slide 41

## Harder 1-dimensional dataset

That's wiped the smirk off SVM's face.

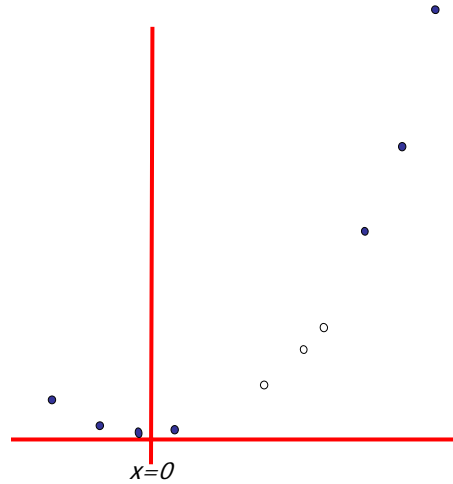
What can be done about this?



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Support Vector Machines: Slide 42

## Harder 1-dimensional dataset



Remember how  
permitting non-  
linear basis  
functions made  
linear regression  
so much nicer?

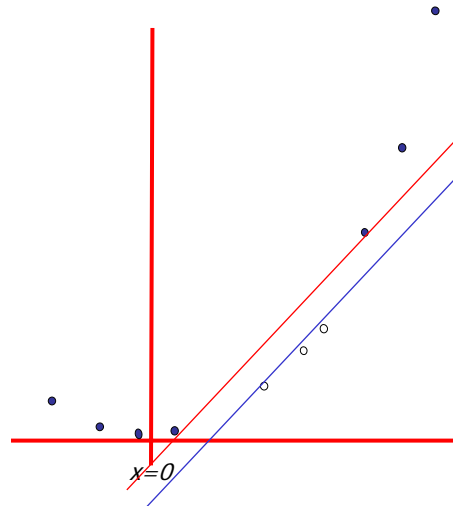
Let's permit them  
here too

$$\mathbf{z}_k = (x_k, x_k^2)$$

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Support Vector Machines: Slide 43

## Harder 1-dimensional dataset



Remember how  
permitting non-  
linear basis  
functions made  
linear regression  
so much nicer?

Let's permit them  
here too

$$\mathbf{z}_k = (x_k, x_k^2)$$

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Support Vector Machines: Slide 44

## Common SVM basis functions

$\mathbf{z}_k =$  ( polynomial terms of  $\mathbf{x}_k$  of degree 1 to  $q$  )

$\mathbf{z}_k =$  ( radial basis functions of  $\mathbf{x}_k$  )

$$\mathbf{z}_k[j] = \varphi_j(\mathbf{x}_k) = \text{KernelFn}\left(\frac{\|\mathbf{x}_k - \mathbf{c}_j\|}{KW}\right)$$

$\mathbf{z}_k =$  ( sigmoid functions of  $\mathbf{x}_k$  )

This is sensible.

Is that the end of the story?

No...there's one more trick!

## Quadratic Basis Functions

$$\Phi(\mathbf{x}) = \begin{pmatrix} 1 \\ \sqrt{2}x_1 \\ \sqrt{2}x_2 \\ \vdots \\ \sqrt{2}x_m \\ x_1^2 \\ x_2^2 \\ \vdots \\ x_m^2 \\ \sqrt{2}x_1x_2 \\ \sqrt{2}x_1x_3 \\ \vdots \\ \sqrt{2}x_1x_m \\ \sqrt{2}x_2x_3 \\ \vdots \\ \sqrt{2}x_1x_m \\ \vdots \\ \sqrt{2}x_{m-1}x_m \end{pmatrix}$$

} Constant Term  
} Linear Terms  
} Pure Quadratic Terms  
} Quadratic Cross-Terms

Number of terms (assuming  $m$  input dimensions) =  $(m+2)\text{-choose-}2$

$$= (m+2)(m+1)/2$$

$$= (\text{as near as makes no difference}) m^2/2$$

You may be wondering what those  $\sqrt{2}$ 's are doing.

- You should be happy that they do no harm

- You'll find out why they're there soon.

# QP with basis functions

Warning: up until Rong Zhang spotted my error in Oct 2003, this equation had been wrong in earlier versions of the notes. This version is correct.

Maximize  $\sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl}$  where  $Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$

Subject to these constraints:  $0 \leq \alpha_k \leq C \quad \forall k \quad \sum_{k=1}^R \alpha_k y_k = 0$

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \epsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

# QP with basis functions

Maximize  $\sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl}$  where  $Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$

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Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \epsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

We must do  $R^2/2$  dot products to get this matrix ready.

Each dot product requires  $m^2/2$  additions and multiplications

The whole thing costs  $R^2 m^2 / 4$ .  
Yeeks!

**...or does it?**

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$



# Quadratic Dot Products

$$\Phi(\mathbf{a}) \bullet \Phi(\mathbf{b}) =$$

$$\begin{pmatrix} 1 \\ \sqrt{2}a_1 \\ \sqrt{2}a_2 \\ \vdots \\ \sqrt{2}a_m \\ a_1^2 \\ a_2^2 \\ \vdots \\ a_m^2 \\ \sqrt{2}a_1a_2 \\ \sqrt{2}a_1a_3 \\ \vdots \\ \sqrt{2}a_1a_m \\ \sqrt{2}a_2a_3 \\ \vdots \\ \sqrt{2}a_1a_m \\ \vdots \\ \sqrt{2}a_{m-1}a_m \end{pmatrix} \bullet \begin{pmatrix} 1 \\ \sqrt{2}b_1 \\ \sqrt{2}b_2 \\ \vdots \\ \sqrt{2}b_m \\ b_1^2 \\ b_2^2 \\ \vdots \\ b_m^2 \\ \sqrt{2}b_1b_2 \\ \sqrt{2}b_1b_3 \\ \vdots \\ \sqrt{2}b_1b_m \\ \sqrt{2}b_2b_3 \\ \vdots \\ \sqrt{2}b_1b_m \\ \vdots \\ \sqrt{2}b_{m-1}b_m \end{pmatrix}$$

$$\begin{aligned} & 1 \\ & + \sum_{i=1}^m 2a_i b_i \\ & + \sum_{i=1}^m a_i^2 b_i^2 \\ & + \sum_{i=1}^m \sum_{j=i+1}^m 2a_i a_j b_i b_j \end{aligned}$$

# Quadratic Dot Products

$$\Phi(\mathbf{a}) \bullet \Phi(\mathbf{b}) =$$

$$1 + 2 \sum_{i=1}^m a_i b_i + \sum_{i=1}^m a_i^2 b_i^2 + \sum_{i=1}^m \sum_{j=i+1}^m 2a_i a_j b_i b_j$$

Just out of casual, innocent, interest, let's look at another function of  $\mathbf{a}$  and  $\mathbf{b}$ :

$$\begin{aligned} & (\mathbf{a} \cdot \mathbf{b} + 1)^2 \\ & = (\mathbf{a} \cdot \mathbf{b})^2 + 2\mathbf{a} \cdot \mathbf{b} + 1 \\ & = \left( \sum_{i=1}^m a_i b_i \right)^2 + 2 \sum_{i=1}^m a_i b_i + 1 \\ & = \sum_{i=1}^m \sum_{j=1}^m a_i a_j b_i b_j + 2 \sum_{i=1}^m a_i b_i + 1 \\ & = \sum_{i=1}^m (a_i b_i)^2 + 2 \sum_{i=1}^m \sum_{j=i+1}^m a_i a_j b_i b_j + 2 \sum_{i=1}^m a_i b_i + 1 \end{aligned}$$

# Quadratic Dot Products

$$\Phi(\mathbf{a}) \cdot \Phi(\mathbf{b}) = 1 + 2 \sum_{i=1}^m a_i b_i + \sum_{i=1}^m a_i^2 b_i^2 + \sum_{i=1}^m \sum_{j=i+1}^m 2 a_i a_j b_i b_j$$

Just out of casual, innocent, interest, let's look at another function of  $\mathbf{a}$  and  $\mathbf{b}$ :

$$\begin{aligned} & (\mathbf{a} \cdot \mathbf{b} + 1)^2 \\ &= (\mathbf{a} \cdot \mathbf{b})^2 + 2\mathbf{a} \cdot \mathbf{b} + 1 \\ &= \left( \sum_{i=1}^m a_i b_i \right)^2 + 2 \sum_{i=1}^m a_i b_i + 1 \\ &= \sum_{i=1}^m \sum_{j=1}^m a_i b_i a_j b_j + 2 \sum_{i=1}^m a_i b_i + 1 \\ &= \sum_{i=1}^m (a_i b_i)^2 + 2 \sum_{i=1}^m \sum_{j=i+1}^m a_i b_i a_j b_j + 2 \sum_{i=1}^m a_i b_i + 1 \end{aligned}$$

They're the same!  
And this is only  $O(m)$  to compute!

## QP with Quadratic basis

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$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$$

Subject to these constraints:  $0 \leq \alpha_k \leq$

We must do  $R^2/2$  dot products to get this matrix ready.  
Each dot product now only requires  $m$  additions and multiplications

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \epsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

$$\text{where } K = \arg \max_k \alpha_k$$

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

## Higher Order Polynomials

Poly-nomial	$\phi(\mathbf{x})$	Cost to build $Q_{kl}$ matrix traditionally	Cost if 100 inputs	$\phi(\mathbf{a}) \cdot \phi(\mathbf{b})$	Cost to build $Q_{kl}$ matrix sneakily	Cost if 100 inputs
Quadratic	All $m^2/2$ terms up to degree 2	$m^2 R^2 / 4$	2,500 $R^2$	$(\mathbf{a} \cdot \mathbf{b} + 1)^2$	$m R^2 / 2$	50 $R^2$
Cubic	All $m^3/6$ terms up to degree 3	$m^3 R^2 / 12$	83,000 $R^2$	$(\mathbf{a} \cdot \mathbf{b} + 1)^3$	$m R^2 / 2$	50 $R^2$
Quartic	All $m^4/24$ terms up to degree 4	$m^4 R^2 / 48$	1,960,000 $R^2$	$(\mathbf{a} \cdot \mathbf{b} + 1)^4$	$m R^2 / 2$	50 $R^2$

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Support Vector Machines: Slide 53

## QP with Quintic basis functions

We must do  $R^2/2$  dot products to get this matrix ready.

In 100-d, each dot product now needs 103 operations instead of 75 million

But there are still worrying things lurking away. *What are they?*

constraints.

$$Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$$

$$\forall k \quad \sum_{k=1}^R \alpha_k y_k = 0$$

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

$$\text{where } K = \arg \max_k \alpha_k$$

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

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Support Vector Machines: Slide 54

## QP with Quintic basis functions

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constraints.

$$Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$$

$$\forall k \quad \sum_{l=1}^R \alpha_k y_k = 0$$

- The fear of overfitting with this enormous number of terms

- The evaluation phase (doing a set of predictions on a test set) will be very expensive (*why?*)

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

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Support Vector Machines: Slide 55

## QP with Quintic basis functions

We must do  $R^2/2$  dot products to get this matrix ready.

In 100-d, each dot product now needs 103 operations instead of 75 million

But there are still worrying things lurking away. What are they?

constraints.

$$Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$$

The use of Maximum Margin *magically* makes this not a problem

$$\forall k \quad \sum_{l=1}^R \alpha_k y_k = 0$$

- The fear of overfitting with this enormous number of terms

- The evaluation phase (doing a set of predictions on a test set) will be very expensive (*why?*)

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where  $K = \arg \max_k \alpha_k$

Because each  $\mathbf{w} \cdot \phi(\mathbf{x})$  (see below) needs 75 million operations. *What can be done?*

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

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Support Vector Machines: Slide 56

## QP with Quintic basis functions

We must do  $R^2/2$  dot products to get this matrix ready.

In 100-d, each dot product now needs 103 operations instead of 75 million

But there are still worrying things lurking away. What are they?

constraints.

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$\begin{aligned} \mathbf{w} \cdot \Phi(\mathbf{x}) &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}) \\ &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k (\mathbf{x}_k \cdot \mathbf{x} + 1)^5 \end{aligned}$$

Only  $Sm$  operations ( $S=\#\text{support vectors}$ )

$$Q_{ij} = y_i y_j (\Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j))$$

The use of Maximum Margin **magically** makes this not a problem

$$\forall k \quad \sum \alpha_k y_k = 0$$

•The fear of overfitting with this enormous number of terms

•The evaluation phase (doing a set of predictions on a test set) will be very expensive (why?)

Because each  $\mathbf{w} \cdot \phi(\mathbf{x})$  (see below) needs 75 million operations. What can be done?

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \phi(\mathbf{x}) - b)$$

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Support Vector Machines: Slide 57

## QP with Quintic basis functions

We must do  $R^2/2$  dot products to get this matrix ready.

In 100-d, each dot product now needs 103 operations instead of 75 million

But there are still worrying things lurking away. What are they?

constraints.

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$\begin{aligned} \mathbf{w} \cdot \Phi(\mathbf{x}) &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}) \\ &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k (\mathbf{x}_k \cdot \mathbf{x} + 1)^5 \end{aligned}$$

Only  $Sm$  operations ( $S=\#\text{support vectors}$ )

$$Q_{ij} = y_i y_j (\Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j))$$

The use of Maximum Margin **magically** makes this not a problem

$$\forall k \quad \sum \alpha_k y_k = 0$$

•The fear of overfitting with this enormous number of terms

•The evaluation phase (doing a set of predictions on a test set) will be very expensive (why?)

Because each  $\mathbf{w} \cdot \phi(\mathbf{x})$  (see below) needs 75 million operations. What can be done?

When you see this many callout bubbles on a slide it's time to wrap the author in a blanket, gently take him away and murmur "someone's been at the PowerPoint for too long."

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Support Vector Machines: Slide 58

## QP with Quintic basis functions

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where}$$

$$\text{Subject to these constraints: } 0 \leq \alpha_k \leq C$$

Then define:

$$\mathbf{w} = \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k)$$

$$\begin{aligned} \mathbf{w} \cdot \Phi(\mathbf{x}) &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k \Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}) \\ &= \sum_{k \text{ s.t. } \alpha_k > 0} \alpha_k y_k (\mathbf{x}_k \cdot \mathbf{x} + 1)^5 \end{aligned}$$

Only  $S$ m operations ( $S$ =#support vectors)

Andrew's opinion of why SVMs don't overfit as much as you'd think:

No matter what the basis function, there are really only up to  $R$  parameters:  $\alpha_1, \alpha_2, \dots, \alpha_R$ , and usually most are set to zero by the Maximum Margin.

Asking for small  $\mathbf{w} \cdot \mathbf{w}$  is like "weight decay" in Neural Nets and like Ridge Regression parameters in Linear regression and like the use of Priors in Bayesian Regression---all designed to smooth the function and reduce overfitting.

Then classify with:

$$f(\mathbf{x}, \mathbf{w}, b) = \text{sign}(\mathbf{w} \cdot \Phi(\mathbf{x}) - b)$$

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Support Vector Machines: Slide 59

## SVM Kernel Functions

- $K(\mathbf{a}, \mathbf{b}) = (\mathbf{a} \cdot \mathbf{b} + 1)^d$  is an example of an SVM Kernel Function
- Beyond polynomials there are other very high dimensional basis functions that can be made practical by finding the right Kernel Function
  - Radial-Basis-style Kernel Function:

$$K(\mathbf{a}, \mathbf{b}) = \exp\left(-\frac{(\mathbf{a} - \mathbf{b})^2}{2\sigma^2}\right)$$

- Neural-net-style Kernel Function:

$$K(\mathbf{a}, \mathbf{b}) = \tanh(\kappa \mathbf{a} \cdot \mathbf{b} - \delta)$$

$\sigma$ ,  $\kappa$  and  $\delta$  are magic parameters that must be chosen by a model selection method such as CV or VCSR<sup>M</sup>\*

\*see last lecture

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## VC-dimension of an SVM

- Very very very loosely speaking there is some theory which under some different assumptions puts an upper bound on the VC dimension as

$$\left\lceil \frac{\text{Diameter}}{\text{Margin}} \right\rceil$$

- where
  - *Diameter* is the diameter of the smallest sphere that can enclose all the high-dimensional term-vectors derived from the training set.
  - *Margin* is the smallest margin we'll let the SVM use
- This can be used in SRM (Structural Risk Minimization) for choosing the polynomial degree, RBF  $\sigma$ , etc.
  - But most people just use Cross-Validation

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## SVM Performance

- Anecdotally they work very very well indeed.
- Example: They are currently the best-known classifier on a well-studied hand-written-character recognition benchmark
- Another Example: Andrew knows several reliable people doing practical real-world work who claim that SVMs have saved them when their other favorite classifiers did poorly.
- There is a lot of excitement and religious fervor about SVMs as of 2001.
- Despite this, some practitioners (including your lecturer) are a little skeptical.

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## Doing multi-class classification

- SVMs can only handle two-class outputs (i.e. a categorical output variable with arity 2).
- What can be done?
- Answer: with output arity  $N$ , learn  $N$  SVM's
  - SVM 1 learns "Output==1" vs "Output != 1"
  - SVM 2 learns "Output==2" vs "Output != 2"
  - :
  - SVM  $N$  learns "Output== $N$ " vs "Output !=  $N$ "
- Then to predict the output for a new input, just predict with each SVM and find out which one puts the prediction the furthest into the positive region.

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## References

- An excellent tutorial on VC-dimension and Support Vector Machines:  
C.J.C. Burges. A tutorial on support vector machines for pattern recognition. *Data Mining and Knowledge Discovery*, 2(2):955-974, 1998.  
<http://citeseer.nj.nec.com/burges98tutorial.html>
- The VC/SRM/SVM Bible:  
Statistical Learning Theory by Vladimir Vapnik, Wiley-Interscience; 1998

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## What You Should Know

- Linear SVMs
- The definition of a maximum margin classifier
- What QP can do for you (but, for this class, you don't need to know how it does it)
- How Maximum Margin can be turned into a QP problem
- How we deal with noisy (non-separable) data
- How we permit non-linear boundaries
- How SVM Kernel functions permit us to pretend we're working with ultra-high-dimensional basis-function terms